

1 GeometricIntegrators.jl: Geometric Numerical Integration 2 in Julia

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Software

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7 Summary

8 *GeometricIntegrators.jl* is a library of geometric numerical algorithms for the solution of dif-
9 ferential equations in Julia. It provides a unified interface for many different algorithms
10 and various types of equations, such as ordinary differential equations, stochastic differential
11 equations and differential algebraic equations, in particular in Lagrangian (variational) and
12 Hamiltonian (symplectic) form. It aims at providing a comprehensive collection of geometric
13 or structure-preserving algorithms, which can be used either interactively or as computational
14 core in other codes. The library provides both, a high-level interface that requires only very
15 few lines of code to solve an actual problem, and a lean low-level interface that allows for
16 straightforward integration into application codes via the exchange of very small data struc-
17 tures. In both cases, the library leaves maximum control to the user, e.g., with respect to the
18 choice of numerical methods and the setup of linear and nonlinear solvers.

19 Statement of need

20 Differential equations are ubiquitous in science and engineering. Many equations possess
21 geometric features or abstract mathematical structures that need to be preserved in the dis-
22 cretisation in order to obtain reliable simulation results, especially for nonlinear problems and
23 long-time simulations. The preservation of such properties improves stability, bounds global
24 error growth and reduces numerical artefacts ([Blanes & Casas, 2016](#); [Hairer et al., 2006](#);
25 [Leimkuhler & Reich, 2004](#); [Sanz-Serna & Calvo, 1994](#)). Robust, performant and structure-
26 preserving solvers for different types of differential equations are thus needed across many
27 disciplines. *GeometricIntegrators.jl* provides such solvers and makes them available for both
28 direct use as well as integration into other codes. Furthermore, the implemented algorithms
29 can also be used within the *DifferentialEquations.jl* ecosystem ([Rackauckas & Nie, 2017](#)),
30 which is the defacto standard differential equation solver for the Julia programming language
31 ([Bezanson et al., 2017](#)).

32 *GeometricIntegrators.jl* provides a comprehensive library of existing geometric integration as
33 well as non-geometric algorithms, such as explicit, implicit, partitioned and stochastic Runge-
34 Kutta methods, SPARK methods, splitting methods, symplectic methods and variational in-
35 tegrators. Most integrators are implemented in an abstract way that allows for the flexible
36 choice of tableaus, approximation spaces, basis functions, quadrature rules, and thus order of
37 convergence. *GeometricIntegrators.jl* also serves as a testbed for the development and analysis
38 of novel algorithms ([Kraus, 2017, 2020](#); [Kraus & Tyranowski, 2020](#)). Due to the modular
39 structure and the use of the multiple dispatch paradigm, the library can easily be extended,
40 e.g., towards new algorithms or new types of equations. The library is designed to minimize

41 overhead and maximize performance in order to be able to perform simulations with millions or
42 even billions of time steps, facilitating the study of the long-time behaviour of both numerical
43 algorithms and dynamical systems.

44 Other Software

45 A Julia package closely related to *GeometricIntegrators.jl* is *DifferentialEquations.jl* (Rack-
46 auckas & Nie, 2017). Although the two libraries provide similar functionality, their scope is
47 rather different. While *DifferentialEquations.jl* provides a feature-rich ecosystem for the so-
48 lution of differential equations, the focus of *GeometricIntegrators.jl* is on algorithms. In fact,
49 *GeometricIntegrators.jl* can be used as backend for *DifferentialEquations.jl* via *GeometricIn-*
50 *tegratorsDiffEq.jl*.

51 Quality control and contributions

52 *GeometricIntegrators.jl* uses continuous integration testing with all supported versions of Julia
53 on macOS, Linux and Windows via GitHub CI. The tests cover most of the library, checking
54 for the correct functioning of all submodules and convergence of the implemented algorithms.
55 The tests can also be run locally in the Julia's REPL by the command `]test GeometricIn-`
56 `tegrators`.

57 Support and submission of contributions to the library are handled through the GitHub repos-
58 itory via issues or by pull requests.

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63 Tomasz M. Tyranowski provided the initial implementation of stochastic integrators.

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